

Amnesiac Flooding: Synchronous Stateless Information Dissemination

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Introduction

Stateless Protocols

Definition (Stateless Protocol)

A *stateless protocol* is a communications protocol in which no session information is retained by participating nodes.

- Stateless protocols do not utilize local storage
- Big advantage in high volume applications, increasing performance by removing the load caused by retention of session information

Information Dissemination Task

Given: A graph $G = (V, E)$, $v_0 \in V$, and a message m

Task: Disseminate m to all nodes of V

Deterministic Flooding

- Deterministic Flooding
 - ◆ Originator v_0 sends message to all neighbors
 - ◆ A node receiving message for first time sends it to all its neighbors
- Properties
 - ◆ stateful algorithm
 - ▶ each node keeps a record of which messages have already arrived
 - ◆ storage per node \approx number of disseminated messages
 - ◆ nodes cannot detect termination \Rightarrow required storage grows over time
 - ◆ termination in $\epsilon_G(v_0) + 1$ rounds ($\epsilon_G(v_0)$ is maximal distance of v_0 to any other node)

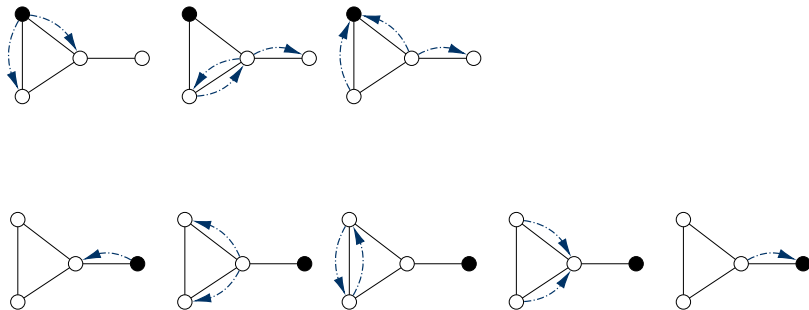
Amnesiac Flooding

- Stateless variant of flooding by Hussak & Trehan [PODC19]
- Only for synchronous systems

Every time a node receives a message, it forwards it to those neighbors from which it didn't receive message in current round

- Difference to classic flooding, a node may forward a message several times

Amnesiac Flooding: Examples



Simple observation: Amnesiac flooding on bipartite graphs terminates in $\epsilon_G(v_0)$ rounds

Amnesiac Flooding: Results

- $Flood_G(v_0)$ denotes number of rounds of \mathcal{A}_{AF} until termination
- \mathcal{A}_{AF} terminates on any finite graph
 - ◆ If G is bipartite graphs: $Flood_G(v_0) = \epsilon_G(v_0)$
 - ◆ Non-bipartite graphs: $Flood_G(v_0) \leq \epsilon_G(v_0) + Diam(G) + 1$
 - ◆ Bound is sharp

Contributions

- Reduction of amnesiac flooding on general graphs to bipartite graphs
 - ◆ Intuitive insights into amnesiac flooding
 - ◆ Simplifies proofs
- Extension of single-source flooding to multi-source flooding
- Sharp upper and lower bounds for termination time for multi-source flooding
- Which k -node subset is an optimal source for amnesiac flooding

Singe-Source Flooding

The Auxiliary Graph $\mathcal{G}(v_0)$

Definition

Denote by $\mathcal{F}(v_0)$ the subgraph of G with node set V and all edges of G that are not cross edges with respect to v_0 .

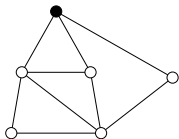
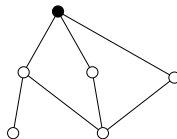


Figure: Graph G

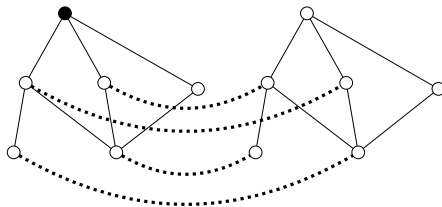
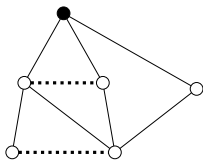


Subgraph $\mathcal{F}(v_0)$

The Auxiliary Graph $\mathcal{G}(v_0)$

Definition

Let $\mathcal{G}(v_0)$ be the graph consisting of two copies of $\mathcal{F}(v_0)$ with node sets V and V' and additionally for any cross edge (u, w) of G the edges (u, w') and (w, u') .



Lemma

$\mathcal{G}(v_0)$ is bipartite.

The Auxiliary Graph $\mathcal{G}(v_0)$

Lemma

A node v receives a message from w in round i in G iff in round i node v receives a message from w in $\mathcal{G}(v_0)$, or v' receives a message from w or from w' in $\mathcal{G}(v_0)$.

Theorem

$Flood_G(v_0) = Flood_{\mathcal{G}(v_0)}(v_0)$ for every $v_0 \in V$.

Corollary

$Flood_G(v_0) = \epsilon_{\mathcal{G}(v_0)}(v_0) \leq \epsilon_G(v_0) + Diam(G) + 1$.

Multi-Source Flooding

Amnesiac Flooding

Algorithm 1: Algorithm \mathcal{A}_{AF} distributes message m in the graph G

input : A graph $G = (V, E)$, a subset S of V , and a message m

Initially: Each node $v \in S$ sends m to each neighbor;

Each node v executes

$M := N(v)$;

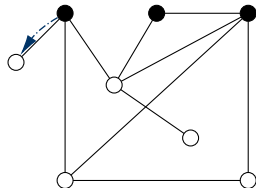
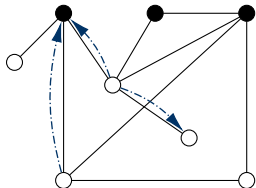
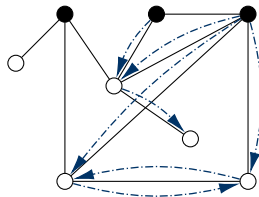
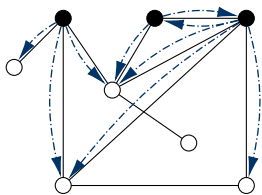
foreach receive(w, m) **do**

$M := M \setminus \{w\}$

if $M \neq N(v)$ **then**

forall $u \in M$ **do** send(u, m);

Amnesiac Flooding: Example



Multi-Source Flooding

Definition

For $S \subseteq V$ denote by $Flood_G(S)$ the number of rounds algorithm \mathcal{A}_{AF} requires to terminate when started by all nodes in S .

Theorem

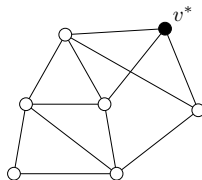
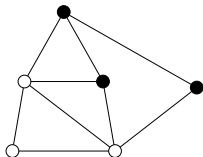
Let $G = (V, E)$ be a connected graph. For every $S \subseteq V$ there is a bipartite graph $\mathcal{G}(S)$ with a node v^* such that $Flood_G(S) = Flood_{\mathcal{G}(S)}(v^*) - 1$.

Corollary

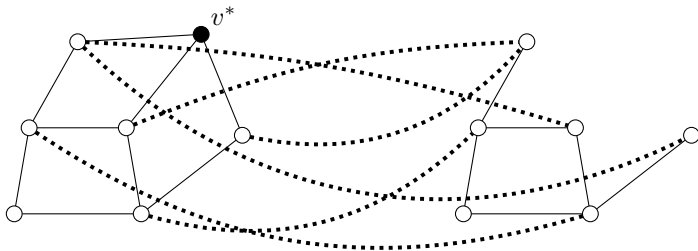
$$Flood_G(S) \leq d(S, V) + 1 + Diam(G)$$

The Graph $\mathcal{G}(S)$

- Let $S \subseteq V$
- Virtual source v^*



The Graph $\mathcal{G}(S)$



Optimal Choice of Flooding Set

Optimal Choice of Flooding Set S

Definition

For $1 \leq k \leq n$ define $Flood_k(G) = \min\{Flood_G(S) \mid S \subseteq V \text{ with } |S| = k\}$

Theorem

Let $G = (V, E)$ be a connected graph.

1. If $k > 1$ then $r_k(G) \leq Flood_k(G) \leq r_k^{ni}(G) + 1 \leq r_{\lfloor k/2 \rfloor}(G) + 1$.
2. $Flood_k(G) = 1$ iff $n = k$ or G is bipartite with $|V_1| = k$ or $|V_2| = k$.
3. $Flood_k(G) \leq 3$ if $k \geq n/2$.

Bipartite Graphs

Theorem

Let $G = (V_1 \cup V_2, E)$ be a connected, bipartite graph. If $k \geq 1$ then

1. $Flood_k(G) = r_k(G)$ iff G has a k -center S with either $S \subseteq V_1$ or $S \subseteq V_2$
2. $Flood_k(G) \leq r_k(G) + 2$
3. If $k \leq \max(|V_1|, |V_2|)$ then $Flood_k(G) \leq r_k(G) + 1$

Conclusion

Conclusion & Outlook

- Construction of a bipartite graph $\mathcal{G}(S)$ such that executions of amnesiac flooding on G and $\mathcal{G}(S)$ are equivalent
- Upper and lower bounds for round complexity of multi-source amnesiac flooding
- Open problems related to amnesiac flooding
 - ◆ Conjecture: If G is connected, non-bipartite then $kFlood_k(G) \geq Rad(G) + k - 1$
 - ◆ $Flood_k(G)$ assumes one of three values in case G is bipartite. Is it possible to infer from structural parameters of G the value of $Flood_k(G)$?
 - ◆ Existence of a stateless asynchronous information dissemination algorithm

Amnesiac Flooding: Synchronous Stateless Information Dissemination

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