Synchronous Concurrent Broadcasts for Intermittent Channels with Bounded Capacities

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Information Dissemination

Single-Source Broadcast

Given: A graph G = (V, E), $v_0 \in V$, and a message *m* located at v_0 Task: Disseminate *m* to all nodes of *V*

Multi-Source Broadcast

Given: A graph G = (V, E), $S \subset V$, and a message *m* located at the nodes of *S* Task: Disseminate *m* to all nodes of *V*

Multi-Message Broadcast

Given: A graph G = (V, E), message m_1, \ldots, m_s located at the nodes v_1, \ldots, v_s Task: Disseminate m_1, \ldots, m_s to all nodes of V

Single-Source Broadcast: Flooding

- Deterministic Flooding
 - Originator sends message *m* to all neighbors
 - Nodes receiving *m* for the first time, send it to all neighbors
 - Flooding is a stateful algorithm
 - Each node keeps a record of which messages have already been received
- Probabilistic Flooding
 - Stateless algorithm
 - Messages are forwarded to neighbors based on a probability
 - Expected number of messages is reduced
- Amnesiac Flooding [PODC19]
 - Stateless deterministic algorithm (synchronous systems)
 - Every time a node receives *m*, it forwards *m* to those neighbors from which it didn't receive *m* in current round

Amnesiac Flooding

Algorithm 1: Algorithm A_{AF} distributes a message in the graph *G*

input : A graph G = (V, E), $v_0 \in V$, and a message m

```
Round 1: v_0 sends m to each neighbor;

Round i > 1: Each node v executes

M := N(v);

foreach receive(w, m) do

\lfloor M := M \setminus \{w\}

if M \neq N(v) then

\lfloor forall u \in M do send(u, m);
```

Amnesiac Flooding: Examples



 \blacksquare \mathcal{A}_{AF} terminates and each message is sent at most twice per edge

Questions

- Can A_{AF} be used for multi-source and multi-message broadcast?
- Yes, if channel capacities are unbounded
- For bounded channel capacities messages must be backed up and send later
- Does A_{AF} terminate in this case?
- Idea: Bounded channels are modelled by intermitted channels

Amnesiac Flooding

- Crucial for termination of A_{AF} :
 - Forwarding of messages is always performed in round immediately following reception
 - \mathcal{A}_{AF} no longer terminates when message forwarding is suspended for some rounds



Figure: Node 2 cannot send messages in rounds 1, 2, 3 and node 3 not in round 1

Contributions

- Algorithm \mathcal{A}_{AFI} :
 - Extension of \mathcal{A}_{AF} to cope with a limited number of channel suspensions
- Proof that A_{AFI} is correct for multi-source broadcasting
- New algorithm for multi-message broadcast



Intermittent Channels

Intermittent Channels

- Basic idea of A_{AFI}
 - If m can't be forwarded in current round, it is postponed until next available round with same parity
 - If blocked round is odd (resp. even), *m* will be forwarded in next available odd (resp. even) round



Round numbers indicate round of reception

Algorithm \mathcal{A}_{AFI}

Algorithm 2: Algorithm A_{AFI} distributes a message *m* in the graph *G*

Initialization

```
parity:= true;
M[true] := M[false] := \bot;
```

```
Each node v executes in every round
Upon receiving message m from w:
M[parity].add(w);
if channel is available and M[parity] \neq \bot then
forall u \in N(v) \setminus M[parity] do send(u, m);
M[parity] := \bot;
parity := \neg parity;
```

function broadcast(*m*)

 $M[parity] := \emptyset;$

Algorithm \mathcal{A}_{AFI}

Theorem

Let G be a graph, A an availability scheme for G, and $f = |\{(v, i) | A(v, i) = false\}|$.

 A_{AFI} delivers a message (resp. terminates) after at most Diam(G) + 2f (resp. 2Diam(G) + 2f + 1) rounds. If G is bipartite each message is forwarded |E| times, otherwise 2|E| times.

Idea of proof:

- For availability scheme A construct a directed bipartite graph $\mathcal{B}_A(v_0)$ such that execution of \mathcal{A}_{AFI} on G with respect to A is equivalent to execution of amnesiac flooding \mathcal{A}_{AF} on $\mathcal{B}_A(v_0)$
- Starting point for construction of $\mathcal{B}_A(v_0)$ is the double cover $\mathcal{G}(v_0)$ of *G*

Double Cover $\mathcal{G}(v_0)$



- Left: *G*: Dashed edges are cross edges (*v*₀ is broadcasting node)
- **Right:** $\mathcal{G}(v_0)$, dashed edges are the replacement edges
- Orientation: Top down, left to right

Predecessors of v in $\mathcal{G}(v_0)$ are copies of nodes in G that send in round i of \mathcal{A}_{AF} a message to v and successors of v in $\mathcal{G}(v_0)$ receive a message from v in round i + 1

The Graph $\mathcal{B}_{A}(v_{0})$

- $\mathcal{G}(v_0)$ is *streched* over time
- \mathcal{B}_A is defined layer by layer
- Nodes of \mathcal{B}_A are of two different types
 - Copies of nodes of $\mathcal{G}(v_0)$ and
 - dummy nodes, they correspond to times when a channel is unavailable
- Execution of \mathcal{A}_{AF} on \mathcal{B}_{A}
 - All nodes including dummy nodes behave according to original A_{AF}
 - No intermitted channels

The Graph $\mathcal{B}_{A}(v_{0})$



Availability scheme A:

 $A(v_2, 1) = A(v_2, 2) = A(v_2, 3) = A(v_3, 1) =$ false and true otherwise.

 \blacksquare \mathcal{B}_A for availability scheme A has four dummy nodes



Conclusion

Conclusion

- Broadcast algorithm A_{AFI} for systems with intermittent channels
- While A_{AFI} is of interest on its own, it is the basis to solve the general task of multi-message broadcasts in systems with bounded channel capacities
- Full paper available at https://arxiv.org/abs/2011

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