

Reliable Model Checking for WSNs





- *Introduction*
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- *Communication characteristics and verification of WSNs*
- *Conclusion and Outlook*

Introduction





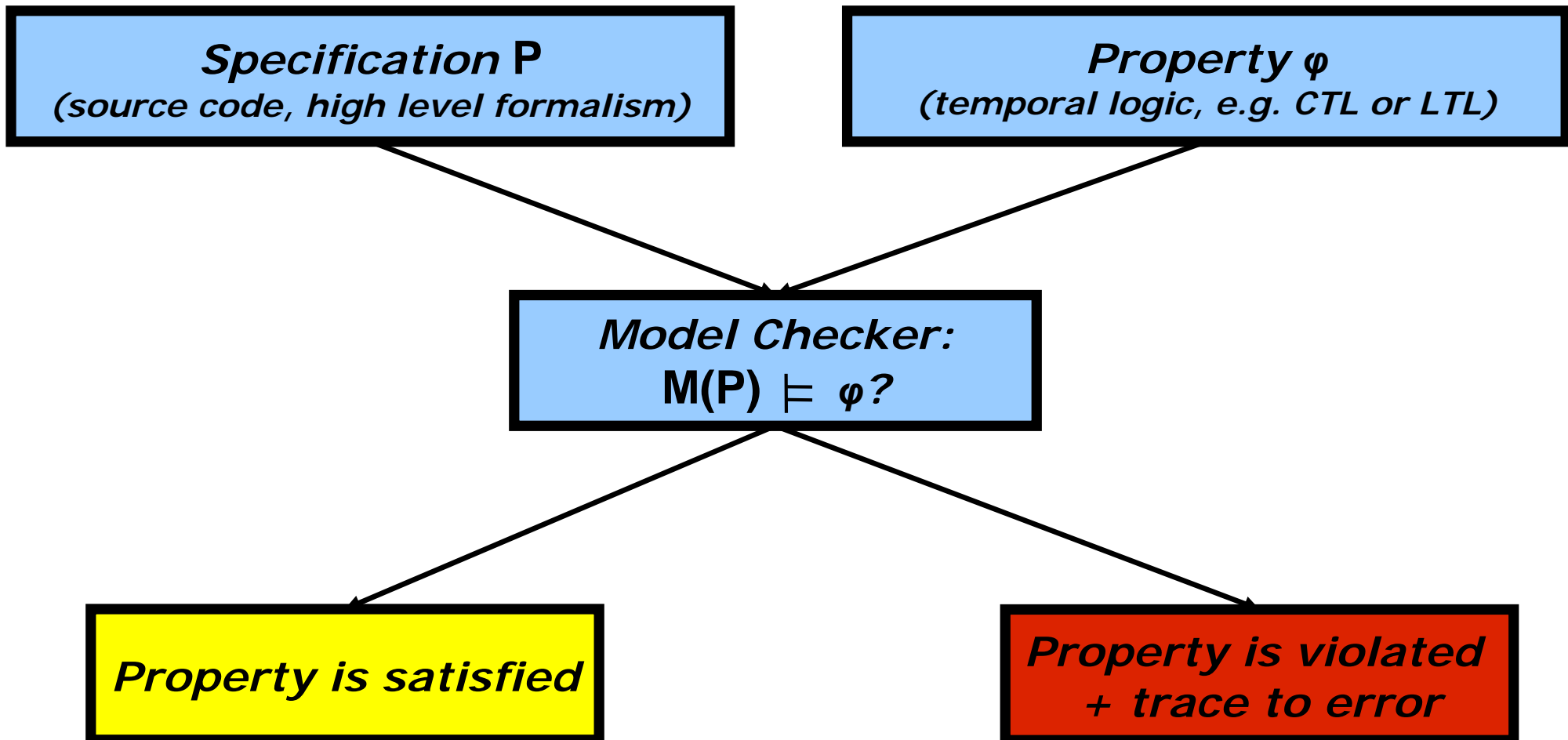
- *Verification techniques:*
 - *Simulation:*
 - *stimulation of a system with input patterns*
 - *check if the system behaves as desired*
 - *no exhaustive analysis of system behavior*
 - *complex errors often cannot be detected*
 - *Formal Verification:*
 - *examination of all possible system behaviors*
 - *allows reliable detection of complex errors*



- *Formal Verification techniques:*
 - *Theorem Proving*
 - *Model Checking*
- *Model Checking:*
 - *fully-automated through tools called **Model Checkers***
 - *given a finite-state model of a system and a formal property, exhaustive investigation whether property holds for that model*
 - *counterexample generation if a property is violated*



- *Model Checking Process:*



Particularities of WSNs with regard to verification





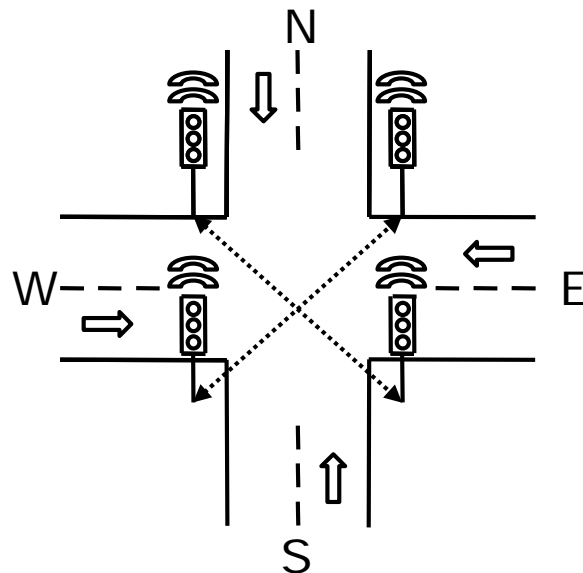
- *Verification of WSNs is a highly non-trivial task*
 - *a single sensor node (hardware+software) can be very complex*
 - *WSNs can consist of a large number of sensor nodes and verification of distributed systems is hard*
- *Additionally communication is wireless*
 - *wireless communication has some particularities, e.g. occurrence of*
 - *transmission errors and collisions*
 - *radio wave propagation variations*

Implementing a traffic light synchronization protocol





- *Case Study: Verification of a traffic light synchronization protocol at 4-way road intersections with the Model Checker NuSMV*



*road intersection
with traffic lights*

**Important safety-critical
property:**

→ **only diagonally
arranged traffic
lights can show green or
yellow at the same
time**

Other desirable properties:

→ *no deadlock*

→ *fair allocation of green phases*

Communication characteristics and verification of WSNs





- *Extract of the verification model for the traffic light at north:*

init(cState) := red;

next(cState) :=

case

state = red & sendReqSouth & !collision : recAck1;

state = red & (sendReqEast | sendReqWest) & !collision : prepAck;

state = red & chanFree & changeAllowed=yes & boolInput : sendReq;

state = sendReq : recAck1;

state = recAck1 & sendAckEast & !collision : ackEast;

state = recAck1 & sendAckWest & !collision : ackWest;

state = recAck1 & (sendReqEast | sendReqWest) & !collision : prepAck;

state = ackEast & sendAckWest & !collision & !(changeAllowed=partner) :

ackPartner;

state = ackWest & sendAckEast & !collision & !(changeAllowed=partner) :

ackPartner;

state = ackPartner & sendAckSouth & !collision : yellow;

state = prepAck & boolInput & chanFree : sendAck;

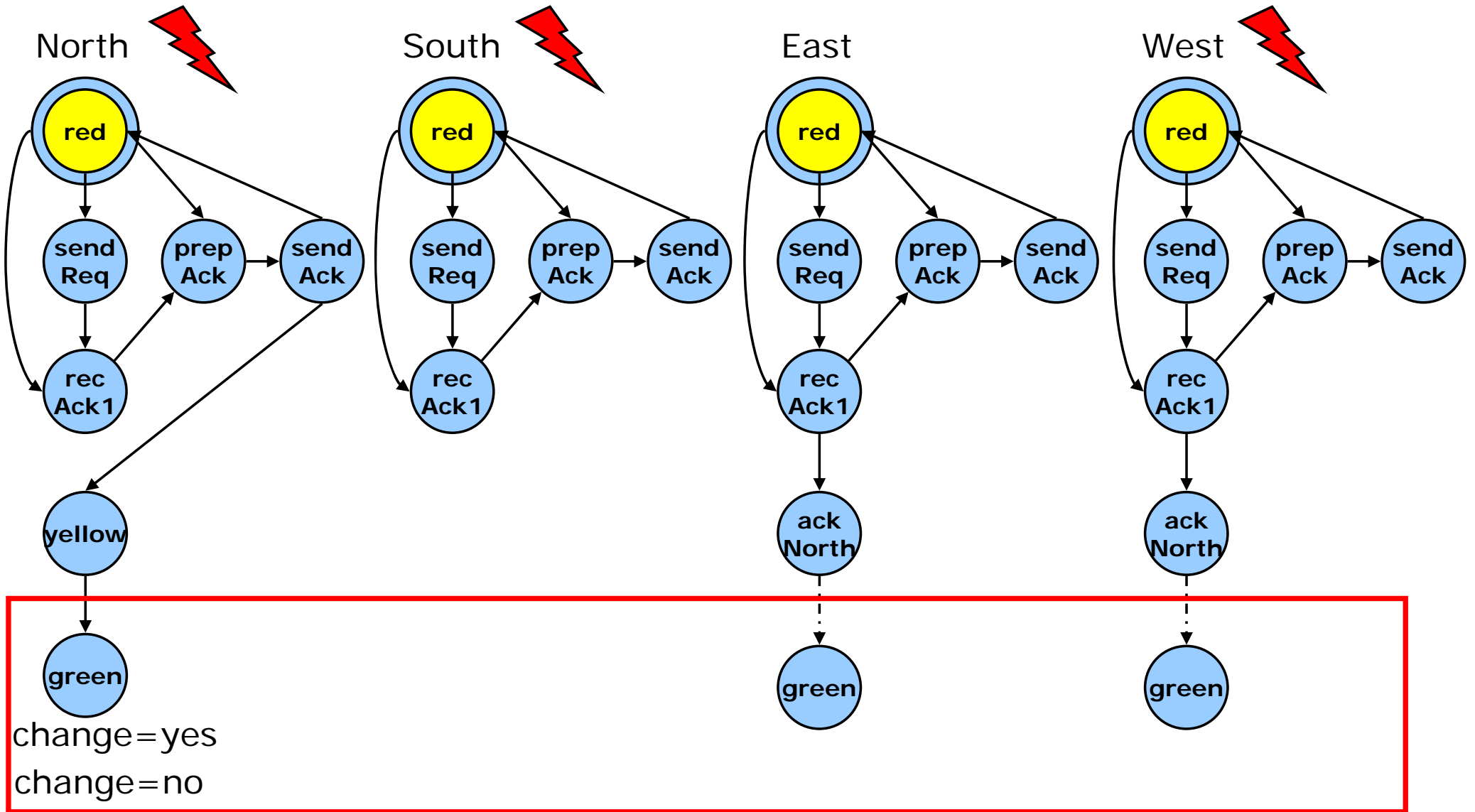
state = sendAck & changeAllowed=partner : yellow;

state = sendAck & !(changeAllowed=partner) : red;

state = yellow & direction=down : green;



- *Non-observance of variations of radio wave propagation*





- *Non-observance of variations of radio wave propagation can circumvent the detection of safety-critical errors*
- *For reliable verification of WSNs it's necessary to include them in the verification model*
- *Because of the state space explosion problem abstract models which contain at least all relevant behaviors are necessary*
- *In our work we have developed some suitable abstractions, e.g. for*
 - *variations of radio wave propagation*
 - *a MAC protocol with carrier sense and a randomized backoff procedure*

Conclusion and Outlook





- *Often system components of WSNs cannot be verified isolated*
- *A model of the communication characteristics can be necessary for reliable verification*
- *Even models of other system components, like e.g. timers or parts of operating systems, could be necessary*
- *Especially for non-verification experts, suitable and faultless abstractions should be available*
- *Future work:*
 - *Development of suitable abstractions for several other WSN components*
 - *Improvement and examination of verifiability of dynamic topologies*

Questions?

